# MTi-630R

- Rugged, IP68-rated AHRS
- 0.2 deg roll/pitch, 1 deg heading accuracy
- Full Graphical User Interface (GUI) and Software Development Kit (SDK) available

The MTi-630R is an Attitude and Heading Reference System with a small form-factor design for deep integration into your application. Building on the proven Xsens MTi 600-series technology it enables a robust and easy to use orientation tracking. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-630R is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.



- White label and OEM integration options available
- 3D models available on request

#### **Sensor Fusion Performance**

Roll, Pitch	0.2 deg RMS
Yaw/Heading	1 deg RMS
Strandown Integration (SDI)	Yes

## Gyroscope

Standard full range —————	2000 deg/s
In-run bias stability	8 deg/h
Bandwidth (-3dB)	520 Hz
Noise Density	0.007 °/s/√Hz
g-sensitivity (calibr.)	0.1 º/s/g

#### Accelerometer

Standard full range	10 g
In-run bias stability	10 (x,y) 15(z) μg
Bandwidth (-3dB)	500 Hz
Noise Density	60 μg/√Hz

### Magnetometer

Standard full range	+/- 8 G
Total RMS noise	1 mG
Non-linearity	0.2%
Possilution	0.2E mC

#### **Barometer**

Standard full range —————	300-1250 hPa
Total RMS noise	1.2 Pa
Relative accuracy —	+/- 8 Pa (~0.5m)

This document is informational and not binding.

Complete and detailed specifications are available at 
mtidocs.movella.com

## Mechanical

IP-rating —————	IP68
Operating Temperature ———	-40 to 85 °C
Casing material —————	Aluminum
Mounting orientation ————	No restriction, full 360° in all axes
Dimensions —	56.5x40.9x24.75 mm
Connector —	Main: ODU (AMC HD 12 pins)
Weight ————	75 g
Certifications —————	CE, FCC, RoHS

#### **Electrical**

Input voltage	4.5 to 24V
Power consumption (typ)	 <0.5 W

## Interfaces / IO

Interfaces —————	CAN, RS232
Sync Options	SyncIn, SyncOut, ClockSync
Protocols —————	Xbus, ASCII (NMEA) or CAN
Clock drift	10 ppm (or external)
Output Frequency ————	Up to 2 kHz, 400 Hz SDI
Built-in-self test —	Gyr, Acc, Mag, Baro

<b>Software Suite</b>	
GUI (Windows/Linux)	MT Manager, Firmware updater,
	Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo,
	public source code
Drivers ————	LabVIEW, ROS, GO
Support —————	Online manuals, community and
	knowledge base



