MTi-680G

- Rugged, IP68 rated RTK GNSS/INS
- 0.2 deg roll/pitch & cm-level position accuracy
- Internal u-blox ZED F9 RTK enabled GNSS receiver

The MTi-680G is an RTK enabled GNSS/INS with a ruggedized housing featuring IP68 protection against environmental influences. Building on the proven Xsens MTi 600-series technology it enables a robust and easy to use cm-level positioning and orientation tracking for outdoor applications. It features a incredibly powerful onboard u-blox ZED F9 RTK GNSS receiver to provide superior positioning performance. It is designed for easy integration and seamless interfacing with other equipment.

The MTi-680G is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.

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Sensor Fusion Performance		Barometer	
Roll, Pitch	0.2 deg RMS	Standard full range	300-1250 hPa
Yaw/Heading	0.5 deg RMS	Total RMS noise	1.2 Pa
Position	1cm+1ppm CEP ¹	Relative accuracy	+/- 8 Pa (~0.5m)
Velocity	0.05m/s RMS	Mechanical	
Gyroscope		IP-rating	IP68
Standard full range	2000 deg/s	Operating Temperature	-40 to 85 °C
In-run bias stability	8 deg/h	Casing material	Aluminum
Bandwidth (-3dB)	520 Hz		No restriction, full 360° in all axes
Noise Density	0.007 °/s/√Hz	Dimensions	56.50x40.90x36.75 mm
g-sensitivity (calibr.)	0.1 º/s/g	Connector	Main: ODU (AMC HD 12 pins)
Accelerometer			RTCM: ODU (AMC HD 4 pins)
Standard full range	10 c		Antenna: SMA
5	10 g	Weight	98 g
In-run bias stability	10 (x,y) 15(z) μg	Certifications	CE, FCC, RoHS
Bandwidth (-3dB)	500 Hz		
Noise Density	60 µg/√Hz	Interfaces / IO	
Magnetometer		Interfaces	CAN, RS232
Standard full range	+/- 8 G	Sync Options	
Total RMS noise	1 mG	Protocols	Xbus, ASCII (NMEA) or CAN
Non-linearity	0.2%	Clock drift	1ppm
Resolution	0.25 mG	Output Frequency	Up to 2kHz, 400 Hz SDI
DTK CNCC Dessiver		Built-in-self test	Gyro, Acc, Mag, Baro, GNSS
RTK GNSS Receiver		Software Suite	
brand	u-blox	GUI (Windows/Linux)	MT Manager, Firmware updater,
Model	ZED F9		Magnetic Field Mapper
RTK correction input	RTCM 3.2/3.3	SDK (Example code)	C++, C#, Python, Matlab, Nucleo,
RTCM input port	RS232 (38K4-921K6 bit/s)		public source code
Electrical		Drivers	LabVIEW, ROS, GO
Input voltage	4.5 to 24V	Support	Online manuals, community and
Power consumption (typ)	<1 W ¹ Depending on GNSS conditio		knowledge base





- White label and OEM integration options available
- 3D models available on request

This document is informational and not binding. Complete and detailed specifications are available at mtidocs.movella.com



Unless stated otherwise, all specifications are typical. Specifications subject to change without notice.